1.2.3 Directives

The following directives are used for system debugging:

Directive	Function
db_system	Control a system
db_level	Set minimum Processor mask level

1.2.4 DB_SYSTEM

NAME

db_system -- "Control a System During Debug"

SYNOPSIS

wint db_system (cpu, mode)

```
uint cpu; /* Designates a cpu in the system */
uint mode; /* new mode */
```

DESCRIPTION

The cpu parameter uniquely identifies a cpu in the system.

The mode parameter indicates what processing may continue in the system after an exception occurs at some point within the system. Valid mode settings are:

DB_SYSTEM_CONTROL to DB_SYSTEM_RELEASE to DB_LEVEL blo DB_ALL blo DB_CONTINUE con

to establish control over system to remove control over system block tasking at level of ISR block all task dispatching continue execution on the system

If an exception occurs while a task is executing, then that task is blocked and a message is sent to the debug task. If DB_LEVEL was specied as the mode, then only this task will be blocked. If DB_ALL was specified as the mode, then all dispatching will be suspended until a db_system command is specified with mode set to DB_CONTINUE.

If an exception occurs while an ISR is executing, further system activity is indicated by the mode parameter. If DB_LEVEL is specified for the mode parameter, then when an exception occurs in an ISR, the executive will issue a db_level directive with the level set to that of the current interrupt priority mask. This will keep the executive from dispatching tasks whose interrupt priority mask is less than this value, and will also block interrupts at this level or less. Interrupts and tasks whose level is greater will occur normally.

If the mode parameter is DB_ALL and an exception occurs within an ISR, then all further activity on this system will be blocked. The only exception to this is that remote requests for RTEID directives (including debug extensions) will be serviced by the executive. The executive will become unblocked when the debug task (remotly) issues a db_unblock for the cpu_id corresponding to the system. At this point, the ISR that caused the exception will continue execution.

Issuing a db_system directive with mode set to DB_CONTINUE will cause the execution of the system to continue.

RETURN VALUE

If db_system is successful, then 0 is returned.

If the call was not successful, an error code is returned.

ERROR CONDITIONS

Invalid cpu.

Invalid mode.

NOTES

When first establishing control over a system, the mode parameter must include DB_SYSTEM_CONTROL and may also include either DB_ALL or DB_LEVEL.

Once control has been established, the type of control may be changed by specifying a different mode.

1.2.5 DB_LEVEL

NAME

db_level -- "Set the Minimum Mask Level"

SYNOPSIS

uint db_level (level, &plevel)

```
uint level; /* Minimum Processor Interrupt mask level*/
uint plevel; /* Previous level - returned by this call */
```

DESCRIPTION

The db_level directive specifies a minimum interrupt priority mask level for further execution of the tasks and ISR's executing on the local cpu.

The level value is the minimum interrupt level for all tasks in the system. The executive will never set the status register's interrupt mask to a value less than level. Furthermore, the executive will never dispatch a task whose status register's interrupt mask is less than level.

RETURN VALUE

If db_level is successful, then the previous minimum level is returned in plevel and 0 is returned.

If the call was not successful, an error code is returned.

ERROR CONDITIONS

Level is not in a valid range (0..7).

The interrupt mask of the current task is less than level.

NOTES

May cause a preempt.

1.3 System Monitoring

Debugging a system involves more than debugging a collection of tasks; the performance of the entire system needs to be monitored and tuned. The db_get_id directive will return a unique identifier for items of particular types, or items in particular queues. The db_get_item directive will get information about items specified by the identifier. The information block will contain data about the system as well as some history (such as total number of calls to a directive) about the execution of the system. It is important to note that gathering statistics about the system will add a small amount of overhead to all of the calls.

The db_get_id directive requires an item_id as an input parameter. If the value of item_id is zero, then the first item of the specified class would be returned. If the item is non-zero, then the next item past the specified item_id will be returned. This can be used to loop through all items in a particular class. For example, to examine all tasks in the system, the following C code could be used:

```
for( item_id=0; item_id=get_item(item_id, TASK, 0); )
{
    process(item_id);
}
```

The class parameter specifies what type of item id to return and the third parameter is used to specify additional information (such as which message queue).

1.3.1 Directives

The directives provided by the system monitoring are:

Directive	Function
db_get_id	Get identifier for an item
db_get_item	Get information about an item