Debug Extension

to the

Real Time Executive Interface Definition

DRAFT 2.0

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# Abstract:

This specification defines a basic set of functions that constitute the Debug Extension to the Real Time Executive Interface Definition. Draft 2.0 is for public review. MOTOROLA retains the right to modify this definition as appropriate during implementation. Draft 2.0 will be submitted to the VITA technical committee no later than 01/25/88.

**PRELIMINARY** 

# DISCLAIMER

This Debug Extension to the Real Time Executive Interface Definition specification is being proposed to be used as the basis for formal standardization by the VME International Trade Association (VITA). However, since the standardization process has just begun, any standard resulting from this document might be different from this document. Any Product designed to this document might not be compatible with the final standard. responsibility is assumed for such incompatibilities and no liability is assumed for any product built to conform to this document.

While considerable effort has been expended to make this document comprehensive, reliable, and unambiguous, it is still being published in preliminary form for public study and comment.

This document is prepared by Motorola Inc., Microcomputer Division. Interest in the Debug Extension to the RTEID is welcome and encouraged. Any technical questions, suggestions or comments may be directed to:

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## 1. DEBUG EXTENSIONS

The debug extensions to the RTEID support several features targeted for use in debugging tasks and interrupt service routines (ISR's). Since debugging is inherently non-real time, systems running under debug control may not exhibit true real time performance.

# 1.1 Debugging Tasks

Most debugging can be performed by debugging a task or a collection of tasks. In this type of debugging, the actual debug task can reside on the local cpu, or it can be remote if the appropriate GLOBAL flags are set.

# 1.1.1 Controlling Tasks

The relationship between the debug task and the task being debugged is established using the  $db\_control$  directive in the "set" mode. The task issuing the  $db\_control$  directive in the set mode must provide a message queue. This message queue is used to communicate between the executive and the task that issued the  $db\_control$  directive. After completion of the  $db\_control$  directive, the task being debugged becomes controlled, and cannot compete for processor time unless directed to execute by the debug task using the  $db\_unblock$  directive. The  $db\_block$  directive is used to block execution of the controlled task. The  $db\_control$  directive in the "clear" mode is used to terminate the relationship between the debug task and the controlled task.

## 1.1.2 Read/Write Memory

To read and write memory belonging to the controlled task the pair of directives  $db\_getmem$  and  $db\_setmem$  are provided.  $Db\_getmem$  reads memory from an address of the controlled task and copies it to a buffer provided by the debug task for a length specified by the debug task.  $Db\_setmem$  writes memory to an address of the controlled task copying it from a buffer provided by the debug task for a length specified by the debug task.

#### 1.1.3 Read/Write Registers

To read and write the processor registers belonging to the controlled task the pair of directives db\_getreg and db\_setreg are provided. Db\_getreg reads a register belonging to the controlled task and copies it to a buffer provided by the debug task. Db\_setreg writes to a register belonging to the controlled task by copying it from a buffer provided by the debug task.

## 1.1.4 Exceptions in Tasks

When a controlled task issues an exception, such as a bus error, the executive will prevent further execution by placing the controlled task in a blocked state. The executive will also format a message containing information about the exception and place it on the message queue identified by the debug task in the  $db\_control$  directive.

# 1.1.5 The debug\_msg message queue

The executive requires the ability to inform the debug task about abnormal activity that occurs when a controlled task executes. This is done by using a message queue specified by the debug task when the db\_control directive is issued. This message queue is used to pass information from the executive to the debug task. When a controlled task is running and suffers an exception, the

executive will block further execution of the task, and inform the debug task of the exception by posting a message on the debug\_msg queue. The format of the message is:

Bytes	Meaning
03	Task id of task causing exception.
47	Exceptions vector offset.
811	Address of the Exception Stack Frame
1215	Program counter at the point of the exception

# 1.1.6 Trace and Breakpoint

A fundamental feature in debugging a task or ISR is the ability to control its execution. This is typically done either by causing the controlled task to single step one instruction, or by having the controlled task execute up to a particular breakpoint. With the debug extensions to the RTEID, a debugger can provide these features.

## 1.1.6.1 Trace

In order to single step, or trace, a controlled task, the debugger must manipulate the status register of the controlled task, cause it to resume execution, and then process the resulting exception.

Tracing can be accomplished by the following steps:

- 1. The debug task prevents further execution of the controlled task by issuing a db\_block directive.
- 2. The controlled task's status register is read using the \*\_getreg directive.
- 3. The debug task sets the trace bit in the status register, and writes it back using the fractive.
- 4. The debug task then permits execution of the controlled task by issuing the db\_unblock directive.
- 5. Since the trace bit is set, when the controlled task executes it will take a trace exception.
- 6. When the trace exception occurs, the executive will block further execution of the controlled task and send a message to the debug task using the debug\_msg message queue specified in the db\_control directive.
- 7. The debug task can then receive the message, process it, and continue debugging the task.

#### 1.1.6.2 Breakpoints

Breakpoints are accomplished in a similar fashion.

- 1. Execution of the controlled task is stopped using the db\_block directive.
- 2. The instruction at the breakpoint locations is read and saved using the db\_getmem directive.
- 3. The instruction is replaced with the breakpoint code using the db\_setmem directive.

- 4. The debug task then executes the controlled task with the db\_unblock directive.
- 5. The controlled task will execute until it reaches the breakpoint code. At this point it will take an exception.
- 8. The executive will block further execution of the debug task and post a message to the debug\_msg message queue specified in the db\_control directive.
- 7. The debugger will receive the message and perform the appropriate action.

## 1.1.7 Directives

The directives provided by the debug manager are:

Directive	Function								
db_control	Control a task								
db_remote	Perform directive on remote cpu								
db_block	Prevent a task from running								
db_unblock	Run a task under control								
db_getmem	Get a task's memory								
db_setmem	Set a task's memory								
db_getreg	Get a task's register								
db_setreg	Set a task's register								

## 1.1.8 DB\_CONTROL

#### NAME

db\_control -- "Control a Task During Debug"

#### **SYNOPSIS**

uint db\_control (tid, mode, qid)

```
uint tid; /* task id as returned from t_create or t_ident */
uint mode; /* new mode */
uint qid; /* debug_msg qid */
```

#### DESCRIPTION

Db\_control is used to establish or remove debug control over a task.

The tid parameter specifies the task to be controlled. This task may exist on the local processor, or any remote processor in the multiprocessing configuration if the task was created with the GLOBAL flag set (see t\_create).

The mode specifies what type of action is to be performed when an exception occurs.

```
DB_TASK_CONTROL set to establish control over task clear to remove control over task
```

These values are mutually exclusive.

The message queue identified by the qid parameter is used by the executive to report exceptions to the debug task. This queue must exist and if debugging is to be done on multiple cpu's, then this queue must have been created with the GLOBAL flag set.

## RETURN VALUE

If db\_control successfully completes, 0 is returned.

If the call was not successful, an error code is returned.

## ERROR CONDITIONS

Invalid tid.

Task already under debug control.

NOTES

Not callable from ISR.

Asserting control over a task will place it in the blocked state.

Removing debug control from a task will unblock the task if it was blocked.

Will not cause a preempt when mode is set.

May cause a preempt when mode is clear by unblocking a higher priority task.

## 1.1.9 DB\_REMOTE

# NAME

```
db_remote -- "Remote Request"
```

## **SYNOPSIS**

```
uint db_remote (cpuid, request, &rval, arg1, ..., argN)
```

```
uint cpuid; /* Identifies remote cpu */
uint request; /* Identifies request to be performed */
uint rval; /* Return value of remote call - returned by this call */
uint arg1; /* First argument of request */
uint argN; /* Last argument of request */
```

#### DESCRIPTION

The db\_remote directive will cause a directive to be executed on a remote cpu.

The cpuid identifies the remote cpu, the request specifies which RTED request (including debug extensions) is to be performed, and arg1-argN specify the arguments.

Arg1-argN are the arguments for the request and their meaning is specific to the directive identified by request. Any addresses specific to the calling task are treated as external physical addresses.

## RETURN VALUE

If db\_remote successfully completes, then real contains the return value of the remote directive, and 0 is returned.

If the call was not successful, an error code is returned.

#### **ERROR CONDITIONS**

Invalid cpuid.

Invalid request.

Other error returns are based on the specific directive identified by request.

## NOTES

This request operates as if a task on the remote system issues the request on behalf of the caller. The actual execution of the remote request may be performed by the ISR which processes remote requests, or may be performed by a system task on the target system.

Since not all RTEID directives may be executed on a non-local cpu, the db\_remote directive will provide this function. It is especially important for debuggers which need to create tasks and manage resources on the target cpu.

This directive is also needed to access resources that are local to a remote cpu. For example, this directive could be used to suspend a task which does not have the GLOBAL flag set (assuming the task is local to a remote cpu).

Several directives have the address of return buffers as input parameters. The caller of db\_remote must specify addresses which are external to the target processor (designated by cpuid).

# 1.1.10 DB\_BLOCK

#### NAME

db\_block -- "Prevent a Task Under Debug Control from Running"

## **SYNOPSIS**

mint db\_block (tid)

uint tid; /\* task id as returned from t\_create or t\_ident \*/

#### DESCRIPTION

The  $db\_block$  directive prevents the task identified in the tid field from executing. The controlling relationship must have been previously established using the  $db\_control$  directive.

The task identified in the tid field may exist on the local processor, or any remote processor in the multiprocessing configuration if the task was created with the GLOBAL flag set (see  $t_create$ ).

## RETURN VALUE

If  $db\_block$  is successful, then 0 is returned.

If the call was not successful, an error code is returned.

## ERROR CONDITIONS

Invalid tid.

Task not in controlled state.

Task already blocked.

#### NOTES

Not callable from ISR.

# 1.1.11 DB\_UNBLOCK

## NAME

db\_unblock -- "Release a Task"

## SYNOPSIS

uint db\_unblock (tid)

uint tid; /\* task id as returned from t\_create or t\_ident \*/

## DESCRIPTION

Db\_unblock allows the task identified by the tid field to resume execution under control of the requesting task. The controlling relationship must have been previously established using the db\_control directive.

The task identified in the tid field may exist on the local processor, or any remote processor in the multiprocessing configuration if the task was created with the GLOBAL flag set (see t\_create).

## RETURN VALUE

If db\_unblock is successful, then 0 is returned.

If the call was not successful, an error code is returned.

## ERROR CONDITIONS

Invalid tid.

Task not in controlled state.

Task not blocked.

#### NOTES

Not callable from ISR.

May cause a preempt.

# 1.1.12 DB\_GETMEM

## NAME

```
db_getmem -- "Get a Task's Memory"
```

#### **SYNOPSIS**

mint db\_getmem ( tid, laddr, bufaddr, length )

```
uint tid; /* task id as returned from t_create or t_ident */
char *laddr; /* logical start address */
char *bufaddr; /* buffer address */
uint length; /* length in bytes */
```

#### DESCRIPTION

The executive reads memory from the task identified in the tid field, starting at the task's logical address laddr, and copies it to the buffer identified in the bufaddr field for the length identified in length.

The task identified in the *tid* field may exist on the local processor, or any remote processor in the multiprocessing configuration if the task was created with the GLOBAL flag set (see *t\_create*). This directive may be used to transfer data between a logical address belonging to the task identified by the *tid* and the requesting task's buffer.

## RETURN VALUE

If db\_getmem successfully read the memory into the buffer, then 0 is returned.

If the memory was not successfully read into the buffer, an error code is returned.

# ERROR CONDITIONS

Invalid tid.

Invalid laddr for the task.

Bus Error occurred during the read.

# NOTES

Not callable from ISR.

Will not cause a preempt.

There is no requirement that the task identified by the tid be a controlled task.

Db\_getmem will attempt to only read the requested data and will not access memory beyond the laddr+length. If length is 1, a byte wide read is performed. If length is 2, a word wide read is performed.

# 1.1.18 DB\_SETMEM

## NAME

```
db_setmem -- "Set a Task's Memory"
```

#### **SYNOPSIS**

wint db\_setmem ( tid, laddr, bufaddr, length )

## DESCRIPTION

The executive writes memory to the task identified in the tid field from the buffer identified in the bufaddr starting at the task's logical address laddr field for the length identified in length.

The task identified in the *tid* field may exist on the local processor, or any remote processor in the multiprocessing configuration if the task was created with the GLOBAL flag set (see *t\_create*). This directive may be used to transfer data between any requesting task's buffer and a logical address belonging to the task identified by the *tid*.

## RETURN VALUE

If db\_setmem successfully writes the memory from the buffer, then 0 is returned.

If the memory was not successfully written from the buffer, an error code is returned.

# ERROR CONDITIONS

Invalid tid.

Invalid laddr.

Bus Error occurred during the write.

# NOTES

Not callable from ISR.

Will not cause a preempt.

There is no requirement that the task identified by tid be a controlled task.

Db\_setmem will only read the requested data and will not access memory beyond the laddr+length. If length is 1, a byte wide read is performed. If length is 2, a word wide read is performed.

# 1.1.14 DB\_GETREG

# The regnum field values are:

CCTAT

S_STAT	Task's status byte values:
T_WTMEM	waiting for memory
T_WTMSG	waiting on message queue
T_WTEVT	waiting for event
T_WTSEM	waiting for semaphore
$T_WTTIM$	waiting for timeout
T_WTCTL	waiting on control
D_REG0	Task's Processor Register D0
D_REG1	Task's Processor Register D1
D_REG2	Task's Processor Register D2
D_REG3	Task's Processor Register D3
D_REG4	Task's Processor Register D4
D_REG5	Task's Processor Register D5
D_REG6	Task's Processor Register D6
D_REG7	Task's Processor Register D7
A_REG0	Task's Processor Register A0
A_REG1	Task's Processor Register A1
A_REG2	Task's Processor Register A2
A_REG3	Task's Processor Register A3
A_REG4	Task's Processor Register A4
A_REG5	Task's Processor Register A5

A_REG8 A_REG7	Task's Processor Register A6 Task's Processor Register A7
H_SR H_PC H_VOR H_USP H_ISP H_MSP H_VBR H_CACR H_CAAR	Status Register Program Counter Vector Offset Register User Stack Pointer Interrupt Stack Pointer Master Stack Pointer Vector Base Register Cache Control Register Cache Address Register
H_VBR H_CACR H_CAAR	Vector Base Register Cache Control Register Cache Address Register
FP_REG0 FP_REG1 FP_REG2 FP_REG3 FP_REG4 FP_REG5 FP_REG6 FP_REG7 FPCR FPSR FPIAR	Task's Processor Register FP0 Task's Processor Register FP1 Task's Processor Register FP2 Task's Processor Register FP3 Task's Processor Register FP4 Task's Processor Register FP5 Task's Processor Register FP6 Task's Processor Register FP6 Task's Processor Register FP7 Task's Coprocessor Control Register Task's Coprocessor Status Register Task's Coprocessor Instruction Address Register

# DESCRIPTION

The executive returns the register value in the regptr field for the register identified in the regnum field and the task identified by the tid.

The task identified in the *tid* field may exist on the local processor, or any remote processor in the multiprocessing configuration if the task was created with the GLOBAL flags value set (see *t\_create*).

# RETURN VALUE

If db\_getreg is successful, regptr is filled in and 0 is returned.

If the call was not successful, an error code is returned.

# ERROR CONDITIONS

Invalid tid.

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